

Identification of a time-dependent UV-photon source in an interstellar cloud

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Abstract

Consider an interstellar cloud that occupies the region $V \subset \mathbb{R}^3$, bounded by the known surface ∂V and assume that the scattering cross section σ_s and the total cross section σ are also known. Then, we prove that it is possible to identify the source $q = q(\mathbf{x}, t)$ that produces UV-photons inside the cloud, provided that the UV-photon distribution function arriving at a location $\hat{\mathbf{x}}$, far from the cloud, is measured at times $\hat{t}_0, \hat{t}_1 = \hat{t}_0 + \tau, \dots, \hat{t}_J = \hat{t}_0 + J\tau$.

Keywords: photon transport, semigroups and linear evolution equations, inverse problems.

1 Introduction

In this paper, we shall consider the following *time dependent inverse problem* in photon transport.

Assume that the boundary surface ∂V of the region $V \subset \mathbb{R}^3$ occupied by an interstellar cloud [1], the scattering cross section σ_s and the total cross section σ are known. If the one-particle distribution function of UV-photons arriving at a location $\hat{\mathbf{x}}$, “far” from the cloud, is measured at times $\hat{t}_0, \hat{t}_1 = \hat{t}_0 + \tau, \dots, \hat{t}_J = \hat{t}_0 + J\tau$, (by using some suitable instrument located within a satellite), then we show that it is possible to identify the *space* and *time* behaviour of the source that produces UV-photons inside the cloud.

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The knowledge of the UV-photon source characteristics is important because, together with the cross sections and the shape of ∂V , determines the form of the photon distribution function. In turn, interaction between UV-photons and the particles of the cloud (mainly hydrogen molecules and dust grains) play a crucial role in the chemistry of the cloud.

Note that the literature on time *independent* inverse problems in particle transport is rather abundant, see the references listed in [2]. Only a few papers deal with *time dependent* inverse problem, see for instance [3, 4, 5, 6, 7]

2 The mathematical model

Let $N(\mathbf{x}, \mathbf{u}, t)$ be the one-particle distribution function of UV-photons which, at time t , are at \mathbf{x} and have velocity $\mathbf{v} = c \mathbf{u}$ (where c is the speed of light). Then, the transport equation, the boundary condition and the initial condition have the form

$$\begin{aligned} \frac{\partial}{\partial t} N(\mathbf{x}, \mathbf{u}, t) = & -c \mathbf{u} \cdot \nabla N(\mathbf{x}, \mathbf{u}, t) - c\sigma N(\mathbf{x}, \mathbf{u}, t) + \\ & + \frac{c\sigma_s}{4\pi} \int_S N(\mathbf{x}, \mathbf{u}', t) d\mathbf{u}' + q(\mathbf{x}, t), \quad \mathbf{x} \in V_i, \mathbf{u} \in S, t > 0 \end{aligned} \quad (1a)$$

$$N(\mathbf{y}, \mathbf{u}, t) = 0 \quad \text{if } \mathbf{y} \in \partial V \quad \text{and} \quad \mathbf{u} \cdot \boldsymbol{\nu}(\mathbf{y}) < 0 \quad (1b)$$

$$N(\mathbf{x}, \mathbf{u}, 0) = N_0(\mathbf{x}, \mathbf{u}), \quad \mathbf{x} \in V, \quad \mathbf{u} \in S \quad (1c)$$

In (1), $V \in \mathbb{R}^3$ is the bounded and convex region occupied by the cloud, and V_i is the interior of V . Hence $V = V_i \cup \partial V$ where ∂V is the boundary surface, which is assumed to be closed and “regular” (in a sense that will be explained later on). Further, S is the surface of the unit sphere, $\mathbf{u} \in S$ is a unit vector, and $\boldsymbol{\nu}(\mathbf{y})$ is

the outward directed normal to ∂V at \mathbf{y} . The scattering cross section σ_s and the total cross section σ (with $\sigma > \sigma_s$) are, for simplicity, assumed to be given positive constants within V (and zero outside).

Finally, $q(\mathbf{x}, t)$ represents the UV-photon source at any $\mathbf{x} \in V$ and $t > 0$ (and $q(\mathbf{x}, t) \equiv 0$ if $\mathbf{x} \notin V$).

In order to write the abstract version of the evolution problem (1) we introduce the Banach space $X = L^1(V \times S)$, with norm $\|f\| = \int_V d\mathbf{x} \int_S |f(\mathbf{x}, \mathbf{u})| d\mathbf{u}$.

Note that $\|N\|$ is the total number of UV-photons within V at time t . We also define the following operators

$$(Bf)(\mathbf{x}, \mathbf{u}) = -c \mathbf{u} \cdot \nabla f(\mathbf{x}, \mathbf{u}) - c\sigma f(\mathbf{x}, \mathbf{u}), \quad R(B) \subset X,$$

$$D(B) = \{f: f \in X, \mathbf{u} \cdot \nabla f \in X, f \text{ satisfies}$$

$$\text{the boundary condition (1b)}\}, \quad (2)$$

$$(Kf)(\mathbf{x}) = \frac{c\sigma}{4\pi} \int_S f(\mathbf{x}, \mathbf{u}') d\mathbf{u}', \quad D(K) = X, \quad R(K) \subset X. \quad (3)$$

In Lemma 2.1, we state the properties of B and K which will be used later on.

Lemma 2.1

i) $K \in \mathcal{B}(X)$, i.e. K is a bounded operator, with $\|K\| \leq c\sigma_s$;

ii) $B \in \mathcal{G}(1, -c\sigma; X)$, i.e. B is the generator of the strongly continuous semigroup

$\{\exp(tB), t \geq 0\}$, such that $\|\exp(tB)\| \leq \exp(-c\sigma t)$, $\forall t \geq 0$.

Proof. *i)* immediately follows from definition (3) whereas *ii)* is a standard result in particle transport theory [8, 9] □

Here, we only recall that the resolvent operator $(I - \tau B)^{-1}$ has the form

$$\begin{aligned} (Gg)(\mathbf{x}, \mathbf{u}) &= ((I - \tau B)^{-1}g)(\mathbf{x}, \mathbf{u}) = \\ &= \frac{1}{\tau c} \int_0^{R(\mathbf{x}, \mathbf{u})} \exp\left(-\frac{1 + \tau c \sigma}{\tau c} r\right) g(\mathbf{x} - r\mathbf{u}, \mathbf{u}) dr \\ &\quad \forall g \in X, \quad \tau > -1/c\sigma \end{aligned} \quad (4a)$$

with

$$\|(I - \tau B)^{-1}\| \leq \frac{1}{1 + \tau c \sigma}. \quad (4b)$$

In (4a), $R(\mathbf{x}, \mathbf{u})$ is such that $\mathbf{y} = \mathbf{x} - R(\mathbf{x}, \mathbf{u})\mathbf{u} \in \partial V$, for each given $\mathbf{x} \in V_i$ and $\mathbf{u} \in S$. In other words, for each given $\mathbf{x} \in V_i$, $\mathbf{y} = \mathbf{x} - R(\mathbf{x}, \mathbf{u})\mathbf{u} \forall \mathbf{u} \in S$ is the equation of the boundary surface ∂V . Such a surface is assumed to be such that $R(\mathbf{x}, \mathbf{u})$ is a continuous function of $(\mathbf{x}, \mathbf{u}) \in V \times S$, with $R(\mathbf{x}, \mathbf{u}) = 0$ if $\mathbf{x} \in \partial V$ and \mathbf{u} is directed towards V_i .

Relation (4a) implies that, $\forall \tau > -1/c\sigma$, the resolvent operator $(I - \tau B)^{-1}$ has the following properties

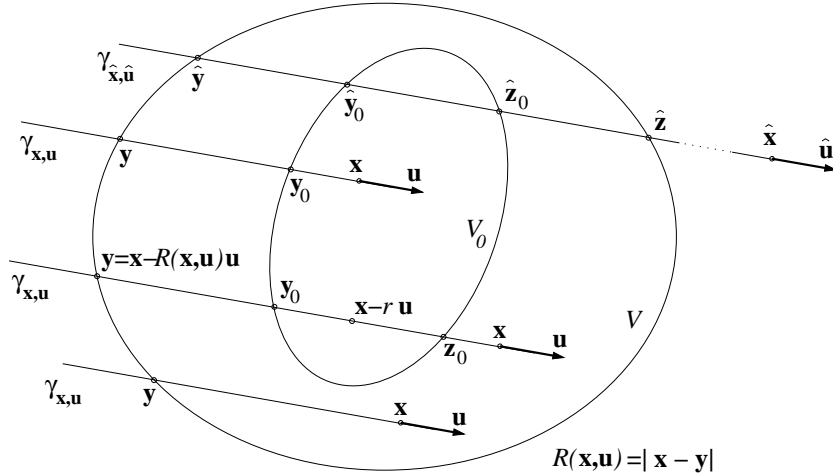


Figure 2.1 The convex regions $V = V_i \cup \partial V$ and $V_0 = V_{0i} \cup \partial V_0$, with

$V_0 \subset V_i$; the location $\hat{\mathbf{x}}$ “far” from the cloud, with $\gamma_{\hat{\mathbf{x}}, \hat{\mathbf{u}}} \cap V_{0i} \neq \emptyset$

Lemma 2.2

- i) $(I - \tau B)^{-1}g \in X_+ \forall g \in X_+$, where $X_+ = \{g: g \in X, g(\mathbf{x}, \mathbf{u}) \geq 0 \text{ at a.a. } (\mathbf{x}, \mathbf{u}) \in V \times S\}$ is the closed positive cone of X ;
- ii) if $g \in X_+$ and $g > 0$ along a finite portion of the half straight line $\gamma_{\mathbf{x}, \mathbf{u}} = \{\mathbf{y}: \mathbf{y} = \mathbf{x} - r\mathbf{u}, r \geq 0\}$, see Figure 2.1, then $((\alpha I - B)^{-1}g(\mathbf{x}, \mathbf{u})) > 0 \forall (\mathbf{x}, \mathbf{u})$.

Consider now the abstract version of system (1), [9]:

$$\begin{cases} \frac{d}{dt}N(t) = (B + K)N(t) + q(t), & t > 0 \\ N(0) = N_0 \end{cases} \quad (5)$$

where $N(t) = N(\cdot, \cdot, t)$ and $q(t) = q(\cdot, t)$ map $[0, \infty)$ into the Banach space X and N_0 is a given element of $D(B + K) = D(B)$.

The unique strict solution of the initial value problem (5) can be written as follows

$$N(t) = \exp(t(B + K))N_0 + \int_0^t \exp((t - s)(B + K))q(s) ds, \quad t \geq 0, \quad (6)$$

where $\{\exp(t(B + K)), t \geq 0\}$ is the semigroup generated by $(B + K)$.

Remark 2.1

- i) By using some standard results of perturbation theory, [8], we have from Lemma 2.1 that $(B + K) \in \mathcal{G}(1, -c(\sigma - \sigma_s); X)$, i.e. $(B + K)$ is the generator of the strongly continuous semigroup $\{\exp(t(B + K))\}$, such that $\|\exp(t(B + K))\| \leq \exp(-c(\sigma - \sigma_s)t) \forall t \geq 0$.
- ii) Relation (6) holds provided that $N_0 \in D(B + K) = D(B)$ and $q(t)$ is a continuously differentiable map from $[0, \infty)$ into X . If $q(t)$ is only continuous, then (6) follows from (5) but the converse is not necessary true, [8].

□

3 The time-discretization procedure

Assume that the source term $q(\mathbf{x}, t)$ in (1a) is strictly positive if $\mathbf{x} \in V_{0i}$, where V_{0i} is the interior of a convex region $V_0 \subset V_i$, bounded by the “regular” surface ∂V_0 , see Fig. 2.1.

Remark 3.1 *The region V_0 is where the stars, emitting the UV-photons, are contained.* □

Suppose also, see the Introduction, that the values $\widehat{N}_j = N(\widehat{\mathbf{x}}, \widehat{\mathbf{u}}, \widehat{t}_j)$ of the UV-photon distribution functions are measured at a location $\widehat{\mathbf{x}}$ far from the cloud (far-field measurements), with $\widehat{\mathbf{u}}$ such that $\gamma_{\widehat{\mathbf{x}}, \widehat{\mathbf{u}}} \cap V_{0i} \neq \emptyset$, see Fig. 2.1, and with $\widehat{t}_j = \widehat{t}_0 + j\tau$, $j = 0, 1, \dots, J$. Then, we have that $\widehat{N}_j = N(\widehat{\mathbf{x}}, \widehat{\mathbf{u}}, \widehat{t}_j) = N(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}, t_j)$ where $\widehat{\mathbf{z}}$ is the “first” intersection of $\gamma_{\widehat{\mathbf{x}}, \widehat{\mathbf{u}}}$ with ∂V and $t_j = \widehat{t}_j - \widehat{t}$ with $\widehat{t} = |\widehat{\mathbf{x}} - \widehat{\mathbf{z}}|/c$. In what follows, we shall choose $\widehat{t}_0 = \widehat{t}$, i.e. $t_0 = 0$ and $t_j = (\widehat{t}_0 + j\tau) - \widehat{t} = j\tau$.

Correspondingly, (6) gives

$$\begin{aligned} \widehat{N}_j = N(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}, t_j) &= \left(\exp(t_j(B + K))N_0 \right)(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \\ &+ \left(\int_0^{t_j} \exp((t_j - s)(B + K))q(s) ds \right)(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}). \end{aligned} \quad (7)$$

However, it is not easy “to extract” some information on the space and time behaviour of the source $q(s) = q(\cdot, s)$ from (7), where the J left-hand sides \widehat{N}_j are assumed to be known, e.g. from experimental measurements.

In fact, it seems much more reasonable to discretize (5) (in a “semi-implicit” way), as follows,[10]

$$\begin{cases} \frac{n_{j+1} - n_j}{\tau} = Bn_{j+1} + KN_j + q(t_j), & j = 0, 1, \dots, J - 1 \\ n_0 = N_0 \end{cases} \quad (8)$$

where $n_j = n_j(\mathbf{x}, \mathbf{u})$ “approximates” $N(\mathbf{x}, \mathbf{u}, t_j) = N_j(\mathbf{x}, \mathbf{u})$. We have from (8),

$\forall(\mathbf{x}, \mathbf{u}) \in V \times S$,

$$\begin{cases} n_{j+1}(\mathbf{x}, \mathbf{u}) = (Gn_j)(\mathbf{x}, \mathbf{u}) + \tau(G[Kn_j + q(t_j)])(\mathbf{x}, \mathbf{u}), & j = 0, 1, \dots, J-1 \\ n_0(\mathbf{x}, \mathbf{u}) = N_0(\mathbf{x}, \mathbf{u}) \end{cases} \quad (9)$$

Remark 3.2

i) As a result of the semi-implicit discretization (8), relation (9) is obtained,

where the explicit form of $G = (I - \tau B)^{-1}$ is known, see (4a).

ii) It can be shown that $\|N_j - n_j\| \leq (\text{a positive constant}) \cdot \tau \forall j$, provided that

$N_0 \in D(B^2)$ and $q(t)$ is regular enough, [10, 11]

4 Identification of the source

Consider the location $\hat{\mathbf{x}}$ “far” from the cloud (hence $\hat{\mathbf{x}} \notin V$) and a unit vector $\hat{\mathbf{u}}$ such that $\gamma_{\hat{\mathbf{x}}, \hat{\mathbf{u}}} \cap V_{0i} \neq \emptyset$, see Figure 2.1. Assume that the photon distribution functions

$N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{t}_0), N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{t}_1), \dots, N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{t}_J)$ are measured. As a consequence,

$N(\hat{\mathbf{z}}, \hat{\mathbf{u}}, t_0) = N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{t}_0), N(\hat{\mathbf{z}}, \hat{\mathbf{u}}, t_1) = N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{t}_1), \dots, N(\hat{\mathbf{z}}, \hat{\mathbf{u}}, t_J) = N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, \hat{t}_J)$ are

known quantities (where we recall that $t_j = \hat{t}_j - \hat{t} = j\tau$, with $\hat{t} = |\hat{\mathbf{x}} - \hat{\mathbf{z}}|/c$ and $\hat{t}_0 = \hat{t}$).

This implies that $n_0(\mathbf{x}, \mathbf{u})$ ($= N_0(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = N(\hat{\mathbf{z}}, \hat{\mathbf{u}}, 0)$), $n_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}), \dots, n_J(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ are also known.

We have from (4a) and (9),

$$n_{j+1}(\mathbf{x}, \mathbf{u}) = (Gn_j)(\mathbf{x}, \mathbf{u}) + \tau(GKn_j)(\mathbf{x}, \mathbf{u})$$

$$\text{if } \mathbf{x} \in V - V_0 \text{ and } \gamma_{\mathbf{x}, \mathbf{u}} \cap V_{0i} = \emptyset \quad (10a)$$

$$n_{j+1}(\mathbf{x}, \mathbf{u}) = (Gn_j)(\mathbf{x}, \mathbf{u}) + \tau(GKn_j)(\mathbf{x}, \mathbf{u}) + (Hq(t_j))(\mathbf{x}, \mathbf{u})$$

$$\text{if } \mathbf{x} \in V - V_0 \text{ and } \gamma_{\mathbf{x}, \mathbf{u}} \cap V_{0i} \neq \emptyset, \text{ or if } \mathbf{x} \in V_{0i}, \quad (10b)$$

where

$$(Hq(t_j))(\mathbf{x}, \mathbf{u}) = \frac{1}{\tau c} \int_{|\mathbf{x}-\mathbf{z}_0|}^{|\mathbf{x}-\mathbf{y}_0|} dr \exp\left(-\frac{1+\tau c \sigma}{\tau c} r\right) q(\mathbf{x} - r\mathbf{u}, t_j)$$

$$\text{if } \mathbf{x} \in V - V_0 \text{ and } \gamma_{\mathbf{x}, \mathbf{u}} \cap V_{0i} \neq \emptyset \quad (10c)$$

$$(Hq(t_j))(\mathbf{x}, \mathbf{u}) = \frac{1}{\tau c} \int_0^{|\mathbf{x}-\mathbf{y}_0|} dr \exp\left(-\frac{1+\tau c \sigma}{\tau c} r\right) q(\mathbf{x} - r\mathbf{u}, t_j) \quad \text{if } \mathbf{x} \in V_{0i} \quad (10d)$$

see Figure 2.1.

In particular, if $\mathbf{x} = \hat{\mathbf{z}}$, $\mathbf{u} = \hat{\mathbf{u}}$ and $\gamma_{\hat{\mathbf{z}}, \hat{\mathbf{u}}} \cap V_{0i} = \gamma_{\hat{\mathbf{x}}, \hat{\mathbf{u}}} \cap V_{0i} \neq \emptyset$, see Figure 2.1, (10b) becomes

$$n_{j+1}(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = (Gn_j)(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + \tau(GKn_j)(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + (Hq(t_j))(\hat{\mathbf{z}}, \hat{\mathbf{u}}). \quad (11)$$

Assume now that $q(\mathbf{x}, t_{j-1})$ is known $\forall \mathbf{x} \in V_0$; then (10a) + (10b), with $j - 1$ instead of j , give $n_j((\mathbf{x}, \mathbf{u}))$ at any $((\mathbf{x}, \mathbf{u})) \in V \times S$. As a consequence, the first and the second term on the r.h.s. of (11) are known, whereas $n_{j+1}(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ is measured (hence, it is also known). Thus, (11) should determine the source term $q(t_j) = q(\cdot, t_j)$, see later on.

In order to understand how (11) identifies the source $q(\mathbf{x}, t_j)$, we re-write (11) as follows

$$n_{j+1}(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = \nu_j(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + Hq(t_j) \quad (12)$$

where $\nu_j(\mathbf{x}, \mathbf{u})$ is the sum of the first two terms on the r.h.s. of (10a), (10b):

$$\nu_j(\mathbf{x}, \mathbf{u}) = (Gn_j)(\mathbf{x}, \mathbf{u}) + \tau(GKn_j)(\mathbf{x}, \mathbf{u}) \quad (13a)$$

and \widehat{H} is defined by

$$\widehat{H}g = (Hg)(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) = \frac{1}{\tau c} \int_{|\widehat{\mathbf{z}} - \widehat{\mathbf{z}}_0|}^{|\widehat{\mathbf{z}} - \widehat{\mathbf{y}}_0|} dr \exp\left(-\frac{1 + \tau c \sigma}{\tau c} r\right) g(\widehat{\mathbf{z}} - r\widehat{\mathbf{u}}), \quad \forall g \in L^\infty(V_0). \quad (13b)$$

Further, we introduce a “suitable” family Φ of source functions $\varphi(\mathbf{x})$, such that

$$(\alpha) \quad \varphi(\mathbf{x}) > 0, \forall \mathbf{x} \in V_{0i}, \varphi(\mathbf{x}) \equiv 0, \forall \mathbf{x} \notin V_{0i};$$

$$(\beta) \quad \varphi \in L^\infty(V_0);$$

$$(\gamma) \quad \text{if } \varphi, \varphi_1 \in \Phi, \text{ then either } \varphi(\mathbf{x}) > \varphi_1(\mathbf{x}) \text{ or } \varphi(\mathbf{x}) < \varphi_1(\mathbf{x}) \quad \forall \mathbf{x} \in V_{0i} \text{ (correspondingly, we shall write } \varphi > \varphi_1 \text{ or } \varphi < \varphi_1);$$

$$(\delta) \quad \text{if } \varphi, \varphi_1 \in \Phi, \text{ then } \varphi_2 = (\varphi + \varphi_1)/2 \in \Phi;$$

$$(\varepsilon) \quad \Phi \text{ is a closed subset of the Banach space } L^\infty(V_0).$$

The family Φ , whose structure might have been suggested by astrophysicists, will be used to find approximate expressions of the J source terms $q(t_j) = q(\cdot, t_j)$, $j = 0, 1, \dots, J - 1$.

Remark 4.1 *Perhaps, the simplest way to construct Φ is the following. Choose the physically reasonable “minimal” and “maximal” sources φ_m and φ_M , satisfying (α) , (β) and such that $\varphi_m(\mathbf{x}) < \varphi_M(\mathbf{x}) \quad \forall \mathbf{x} \in V_{0i}$.*

Then, $\Phi = \Phi_{[0,1]} = \{\varphi_h : \varphi_h = (1 - h)\varphi_m + h\varphi_M, h \in [0, 1]\}$. □

Remark 4.2 If $\varphi_h \in \Phi_{[0,1]}$, we obtain from (13b) that $\widehat{H}\phi_h = (1-h)\widehat{H}\varphi_m + h\widehat{H}\varphi_M$. Then, (12) leads to the value $\widehat{h} \in [0, 1]$ such that $n_{j+1}(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) = \nu_j(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + (1-\widehat{h})\widehat{H}\varphi_m + \widehat{h}\widehat{H}\varphi_M$, where n_{j+1} is measured and ν_j is known. Correspondingly, the approximated value of the same is given by $q(t_j) = q(\cdot, t_j) = (1 - \widehat{h})\varphi_m(\cdot) + \widehat{h}\varphi_M(\cdot)$. \square

Going back to definition (13b) and considering a “general” family Φ , it immediately follows that

$$\widehat{H}\varphi < \widehat{H}\varphi_1, \quad \forall \varphi, \varphi_1 \text{ with } \varphi < \varphi_1. \quad (14)$$

We remark that (14) and the procedure that follows may still hold also if \widehat{H} is *nonlinear* (and, of course, it satisfies suitable assumptions).

As a first step, consider (12) with $j = 0$:

$$n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) = \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}q(t_0). \quad (15)$$

Since the value $n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}})$ of the photon distribution function at time t_1 is known as a result of some experimental procedure and $\nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}})$ is defined by (13a) with $j = 0$ and with n_0 given, assume that $\varphi_{1-} \in \Phi$ and $\varphi_{1+} \in \Phi$ exist, such that

$$n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) > n_{1-} = \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\varphi_{1-}, \quad (16a)$$

$$n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) < n_{1+} = \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\varphi_{1+}. \quad (16b)$$

Note that, if the family Φ is suitably chosen, it should be possible to find φ_{1-} and φ_{1+} such that (16a) and (16b) are satisfied. (Otherwise, if for instance $\Phi = \Phi_{[0,1]}$ of Remark 4.1, one might choose a “smaller” φ_m and a “larger” φ_M .)

Further, consider $\frac{\varphi_{1-} + \varphi_{1+}}{2} \in \Phi$ and assume, for instance, that

$$n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) < \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\left(\frac{\varphi_{1-} + \varphi_{1+}}{2}\right), \quad \text{i.e.} \quad n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) < \frac{n_{1-} + n_{1+}}{2}$$

because of the linearity of \widehat{H} . Then, if we put $\varphi_{2-} = \varphi_{1-}$, $\varphi_{2+} = \frac{\varphi_{1-} + \varphi_{1+}}{2}$, we have

$$\begin{aligned} n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) &> n_{2-} = \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\varphi_{2-} = n_{1-} \\ n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) &< n_{2+} = \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\varphi_{2+} = \frac{n_{1-} + n_{1+}}{2} \end{aligned}$$

and also

$$\varphi_{1-} = \varphi_{2-} < \varphi_{2+} < \varphi_{1+}, \quad n_{1-} = n_{2-} < n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) < n_{2+} < n_{1+}$$

By iterating the above procedure (for which *only* $\widehat{H}\varphi_{1-}$ and $\widehat{H}\varphi_{1+}$ need to be evaluated), we find the four monotone sequences

$$\begin{aligned} \{\varphi_{j-}\} &\subset \Phi \subset L^\infty(V_0), & \{\varphi_{j+}\} &\subset \Phi \subset L^\infty(V_0), \\ \{n_{j-}\} &\subset \mathbb{R}_+, & \{n_{j+}\} &\subset \mathbb{R}_+. \end{aligned}$$

It is not difficult to show, see for instance [12], that φ_{j-} and φ_{j+} are Cauchy sequences in $L^\infty(V_0)$ whereas n_{j-} and n_{j+} are Cauchy sequences in \mathbb{R} . Correspondingly, we have

$$\begin{aligned} \lim_{j \rightarrow \infty} \varphi_{j-} &= \lim_{j \rightarrow \infty} \varphi_{j+} = \varphi_{\infty,1} \in \Phi \quad (\text{because } \Phi \text{ is a closed subset of } L^\infty(V_0)), \\ \lim_{j \rightarrow \infty} n_{j-} &= \lim_{j \rightarrow \infty} n_{j+} = n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}), \\ n_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) &= \nu_0(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\varphi_{\infty,1} \end{aligned} \tag{17}$$

Remark 4.3 According to (17), $\varphi_{\infty,1} \in \Phi$ is the “best approximation” within the family Φ to the “physical” source $q(t_0) = q(\cdot, t_0)$ appearing in (15). Then, going back to (9) with $j = 0$ and putting

$$\tilde{n}_1(\mathbf{x}, \mathbf{u}) = (Gn_0)(\mathbf{x}, \mathbf{u}) + \tau(GKn_0)(\mathbf{x}, \mathbf{u}) + \tau(G\varphi_{\infty,1})(\mathbf{x}, \mathbf{u}), \quad (\mathbf{x}, \mathbf{u}) \in V \times S \tag{18}$$

we conclude that $\tilde{n}_1(\mathbf{x}, \mathbf{u})$ should be a reasonable approximation to $n_1(\mathbf{x}, \mathbf{u})$ at any $(\mathbf{x}, \mathbf{u}) \in V \times S$ (and, of course, $\tilde{n}_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = n_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ because of (17)). \square

As a second step, we consider (12) with $j = 1$:

$$n_2(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = \nu_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + \hat{H}q(t_1), \quad (19)$$

where $n_2(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ is known because it is the value of the photon distribution function, measured at time t_2 . However, since $\nu_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ is given by (13a) with $j = 1$, such a quantity can be evaluated if we know $n_1(\mathbf{x}, \mathbf{u})$ and not only the single value $n_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$. On the other hand, (18) gives $\tilde{n}_1(\mathbf{x}, \mathbf{u})$ which approximates $n_1(\mathbf{x}, \mathbf{u})$. As a consequence, we can evaluate $\tilde{\nu}_1(\mathbf{x}, \mathbf{u})$, defined by (13a) with $j = 1$, $\mathbf{x} = \hat{\mathbf{z}}$, $\mathbf{u} = \hat{\mathbf{u}}$, and with $\tilde{n}_1(\mathbf{x}, \mathbf{u})$ instead of $n_1(\mathbf{x}, \mathbf{u})$. Then, the procedure to identify the source $q(t_1)$ leads to the element $\tilde{\varphi}_{\infty,2} \in \Phi$ such that

$$n_2(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = \tilde{\nu}_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + \hat{H}\tilde{\varphi}_{\infty,2} \quad (20)$$

rather than to the element $\varphi_{\infty,2}$ such that

$$n_2(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = \nu_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + \hat{H}\varphi_{\infty,2}. \quad (21)$$

However, since $\tilde{\nu}_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ should be a good approximation to $\nu_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$, $\tilde{\varphi}_{\infty,2}$ is likely to be “close” to $\varphi_{\infty,2}$, see Section 5.

Further, by using $\tilde{n}_1(\mathbf{x}, \mathbf{u})$ and $\varphi_{\infty,2}(\mathbf{x})$, from (9) with $j = 1$ we have that

$$\tilde{n}_2(\mathbf{x}, \mathbf{u}) = (G\tilde{n}_1)(\mathbf{x}, \mathbf{u}) + \tau(GK\tilde{n}_1)(\mathbf{x}, \mathbf{u}) + \tau(G\tilde{\varphi}_{\infty,2})(\mathbf{x}, \mathbf{u}) \quad (22)$$

should be a reasonable approximation to $n_2(\mathbf{x}, \mathbf{u}) \forall (\mathbf{x}, \mathbf{u}) \in V \times S$. The final result of the above procedure is the set $\{\varphi_{\infty,1}(\mathbf{x}), \tilde{\varphi}_{\infty,2}(\mathbf{x}), \dots, \tilde{\varphi}_{\infty,J}(\mathbf{x})\}$ that is in some sense, the best approximation within the family Φ to the set of the “physical” source terms $\{q(\mathbf{x}, t_0), q(\mathbf{x}, t_1), \dots, q(\mathbf{x}, t_{J-1})\}$.

5 Concluding remarks

1. If the family Φ is particularly well chosen (or it is “large enough”), then the set $\{q(\mathbf{x}, t_0), \dots, q(\mathbf{x}, t_{J-1})\}$ is contained in Φ . Correspondingly, $\varphi_{\infty,1}(\mathbf{x}) = q(\mathbf{x}, t_0)$, $\varphi_{\infty,2}(\mathbf{x}) = \tilde{\varphi}_{\infty,2}(\mathbf{x}) = q(\mathbf{x}, t_1), \dots, \varphi_{\infty,J}(\mathbf{x}) = \tilde{\varphi}_{\infty,J}(\mathbf{x}) = q(\mathbf{x}, t_{J-1})$, due to the uniqueness of our limit procedure within Φ .

Thus, in such a lucky case, we are able to identify *exactly* the source term.

In particular, assume that q depends on t but not on $\mathbf{x} \in V_0$. Then, we can take $\Phi = \{\varphi: q_m \leq \varphi(\mathbf{x}) = \text{a constant} \leq q_M\} \subset \mathbb{R}_+$ and, if q_m and q_M are suitably chosen, the set $\{q(t_0), q(t_1), \dots, q(t_{J-1})\}$ is contained in Φ .

2. Assume now that a family Ψ is also considered, with $\Psi \cap \Phi = \emptyset$ and such that (α) - (ε) of Section 4 are satisfied. Then, the procedures of Section 4 lead to the set $\{\psi_{\infty,1}(\mathbf{x}), \tilde{\psi}_{\infty,2}(\mathbf{x}), \dots, \tilde{\psi}_{\infty,J}(\mathbf{x})\}$ as the best approximation within ψ to the physical source terms $\{q(\mathbf{x}, t_0), \dots, q(\mathbf{x}, t_{J-1})\}$. This kind of non-uniqueness is obviously due to the possibility of choosing among several different families Φ, Ψ, \dots . Of course, the most reasonable choice should be suggested by experimental evidence, e.g. by a partial knowledge of the position of the stars which emit UV-photons inside the cloud.

3. As far as the errors involved in the procedures of Section 4, assume that

- i) the experimental values $n_{j+1}(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ are exact, i.e. they are measured with a very small experimental error, see (12);
- ii) the “true” photon distribution function $n_{j+1}(\mathbf{x}, \mathbf{u})$ is known at any $(\mathbf{x}, \mathbf{u}) \in V \times S$, so that the value $\nu(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ is exact.

If i) and ii) are satisfied, relation (12) is also exact; *assume* that consequently, (12) leads to an approximate source $\varphi_{\infty,j}(\mathbf{x}, \mathbf{u})$ such that

- iii) $\|q(t_j) - \varphi_{\infty,j}\|_{\infty} < \varepsilon$, $j = 0, 1, \dots, J-1$ where $\|\cdot\|_{\infty}$ is the norm in $L^{\infty}(V)$ (we recall that $q(\mathbf{x}, t_j) \equiv 0$ and $\varphi_{\infty,j}(\mathbf{x}) \equiv 0$ if $\mathbf{x} \notin V_{0i}$). Note that iii) should be satisfied if the family Φ is suitably chosen.

Consider now the first step ($j = 0$) of Section 4; starting from (15) (with $n_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ and $\nu_0(\hat{\mathbf{z}}, \hat{\mathbf{u}})$ both exact), and taking into account assumption iii), we identify $\varphi_{\infty,1} \in \Phi$ such that $n_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = \nu_0(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + \hat{H}\varphi_{\infty,1}$, with

$$\|q(t_0) - \varphi_{\infty,1}\| < \varepsilon \quad (23)$$

Consequently, (9) with $j = 1$ and (18) give

$$\begin{aligned} |\tilde{n}_1(\mathbf{x}, \mathbf{u}) - n_1(\mathbf{x}, \mathbf{u})| &\leq \tau \|G\|_{\infty} \|\varphi_{\infty,1}\|_{\infty} \leq \frac{\tau\varepsilon}{1 + c\sigma\tau} \\ \|\tilde{n}_1 - n_1\|_{\infty} &\leq \frac{\tau\varepsilon}{1 + c\sigma\tau} \end{aligned} \quad (24)$$

because definition (4a) also implies that $\|G\|_{\infty} \leq \frac{1}{1 + c\sigma\tau}$. Then, from (13a) with $j = 1$, we obtain that

$$\begin{aligned} |\tilde{\nu}_1(\mathbf{x}, \mathbf{u}) - \nu_1(\mathbf{x}, \mathbf{u})| &\leq |(G(\tilde{n}_1 - n_1)(\mathbf{x}, \mathbf{u}))| + \tau |(GK(\tilde{n}_1 - n_1)(\mathbf{x}, \mathbf{u}))| \leq \\ &\leq \left(\frac{1}{1 + c\sigma\tau} + \frac{\tau c\sigma_s}{1 + c\sigma\tau} \right) \|\tilde{n}_1 - n_1\|_{\infty} \leq \frac{\tau\varepsilon}{1 + c\sigma\tau} \end{aligned} \quad (25)$$

where we recall that $\tilde{\nu}_j$ is defined by (13a) with \tilde{n}_j instead of n_j and where we used (24).

Consider then the second step ($j = 2$) of Section 4; if we knew the exact $\nu_1(\hat{\mathbf{z}}, \hat{\mathbf{u}})$, (19) would lead to the element $\varphi_{\infty,2} \in \Phi$ such that $n_2(\hat{\mathbf{z}}, \hat{\mathbf{u}}) = \nu_1(\hat{\mathbf{z}}, \hat{\mathbf{u}}) + \hat{H}\varphi_{\infty,2}$, with $\|q(t_1) - \varphi_{\infty,2}\|_{\infty} < \varepsilon$.

However, we only know the approximate value $\tilde{\nu}_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}})$ and so we obtain the element $\tilde{\varphi}_{\infty,2} \in \Phi$ such that $n_2(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) = \tilde{\nu}_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) + \widehat{H}\tilde{\varphi}_{\infty,2}$. Thus we have

$$\widehat{H}(\tilde{\varphi}_{\infty,2} - \varphi_{\infty,2}) = \nu_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}) - \tilde{\nu}_1(\widehat{\mathbf{z}}, \widehat{\mathbf{u}}). \quad (26)$$

For simplicity, we shall now assume that the family Φ is defined as in Remark 4.1.

$$\text{iv) } \Phi = \Phi_{[0,1]} = \{\varphi_h: \varphi_h = (1-h)\varphi_m + h\varphi_M, h \in [0,1]\}.$$

Then we have

$$\tilde{\varphi}_{\infty,2} = (1-\tilde{h})\varphi_m + \tilde{h}\varphi_M, \quad \varphi_{\infty,2} = (1-h)\varphi_m + h\varphi_M,$$

$$\widehat{H}(\tilde{\varphi}_{\infty,2} - \varphi_{\infty,2}) = (\tilde{h} - h)\widehat{H}(\varphi_M - \varphi_m).$$

Note that, since both $\tilde{\varphi}_{\infty,2}$ and $\varphi_{\infty,2}$ belong to Φ , either $\tilde{\varphi}_{\infty,2} > \varphi_{\infty,2}$ or $\tilde{\varphi}_{\infty,2} < \varphi_{\infty,2}$. Suppose, for instance, that $\tilde{\varphi}_{\infty,2} > \varphi_{\infty,2}$, i.e. $\tilde{h} > h$.

Then, (25) and (26) give

$$(\tilde{h} - h)\widehat{H}(\varphi_M - \varphi_m) \leq \frac{\tau\varepsilon}{1 + c\sigma\tau}, \quad \tilde{h} - h \leq \frac{\tau\varepsilon}{1 + c\sigma\tau} \frac{1}{\widehat{H}(\varphi_M - \varphi_m)},$$

$$\|\tilde{\varphi}_{\infty,2} - \varphi_{\infty,2}\| \leq \varepsilon\eta, \quad \text{where } \eta = \frac{\tau}{1 + c\sigma\tau} \frac{\|\varphi_M - \varphi_m\|_{\infty}}{\widehat{H}(\varphi_M - \varphi_m)}.$$

It follows that

$$\|q(t_1) - \tilde{\varphi}_{\infty,2}\|_{\infty} \leq \|q(t_1) - \varphi_{\infty,2}\|_{\infty} + \|\varphi_M - \varphi_m\|_{\infty} \leq \varepsilon(1 + \eta). \quad (27)$$

Iterations of the above procedure leads to the inequality

$$\|q(t_j) - \tilde{\varphi}_{\infty,j+1}\|_{\infty} \leq \varepsilon(1 + \eta)^j, \quad j = 0, 1, \dots, J-1,$$

that gives the error with which the set $\{\varphi_{\infty,1}, \tilde{\varphi}_{\infty,2}, \dots, \tilde{\varphi}_{\infty,J}\} \subset \Phi$ approximates the “physical” set of sources $\{q(t_0), q(t_1), \dots, q(t_{J-1})\}$.

4. The algorithm presented in this paper has been recently implemented by S. Pieraccini et al in [13].
5. Assume, for instance, that the two values $N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, t_j)$ and $N(\hat{\mathbf{x}}, \hat{\mathbf{u}}', t_j)$ of the photon distribution function can be measured at $\hat{\mathbf{x}}$, at each t_j , and corresponding to the two directions $\hat{\mathbf{u}}$ and $\hat{\mathbf{u}}'$. This is possible if the interstellar cloud under consideration is seen from the satellite containing the recording instrument under a solid angle which is not “too small”.

Then, a family Φ_1 of source functions ϕ may be chosen as a two-parameter family: $\Phi_1 = \{\varphi: \varphi = \varphi_{h,k}, h \in [0, 1], k \in [0, 1]\}$, where for instance $\varphi_{h,k} = h\varphi_1 + k(1-h)\varphi_2 + (1-k)(1-h)\varphi_3$. Hence, Φ_1 allows a larger choice than the family Φ defined in Remark 4.1.

6. If the measured $N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, t)$ is a continuous function of t , then it is not difficult to prove that $\|\tilde{\varphi}_{\infty,t_{j-1}} - \tilde{\varphi}_{\infty,t_j}\|_{\infty} = 0$ if $t_j \rightarrow t_{j-1}$, with t_{j-1} given. However, some difficulties arise if we let $J \rightarrow \infty$ (i.e. $\tau \rightarrow 0_+$) because it can be shown that the corresponding approximated source $\tilde{\varphi}_{\infty}(\mathbf{x}, t)$ is such that only the total number of photons arriving at \mathbf{x} during some time interval $[0, t^*]$ can be evaluated. In other words, $\tilde{\varphi}_{\infty}$ is such that

$$\int_0^{t^*} n(\hat{\mathbf{x}}, \hat{\mathbf{u}}, t) dt = \int_0^{t^*} N(\hat{\mathbf{x}}, \hat{\mathbf{u}}, t) dt.$$

A further paper will be devoted to study this problem.

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